

[0022] FIG. 3 is an exploded perspective view of the input device of FIG. 1;

[0023] FIG. 4 is an overall perspective view of a PC, which shows a position at which the input device of FIG. 1 is disposed;

[0024] FIG. 5 is a longitudinal sectional view of the essential portion of the PC of FIG. 4;

[0025] FIG. 6 is an exploded perspective view showing details of the input sensor of FIG. 1;

[0026] FIG. 7 is a circuit wiring diagram showing an X electrode layer of FIG. 6;

[0027] FIG. 8 is a plan view showing through holes formed in an insulating film of FIG. 6;

[0028] FIG. 9 is a circuit wiring diagram showing a Y electrode layer of FIG. 6;

[0029] FIG. 10 is a plan view showing another embodiment of a pointing section; and

[0030] FIG. 11 is a longitudinal sectional view showing a conventional input device.

DESCRIPTION OF THE PREFERRED EMBODIMENTS

[0031] FIGS. 1 to 3 show an embodiment of an input device according to the present invention. In this embodiment, an electrostatic-capacitance-type coordinate input device 1 used as a pointing device for a personal computer (PC) has an input sensor 2 formed from a flexible material such as a film. This input sensor 2 is disposed on the rear surface of a housing 4 in a PC 3.

[0032] The input device 1 is of an electrostatic-capacitance type. As shown in FIG. 5, when a conductor such as a finger 11 is brought into contact with or in close proximity to the input sensor 2, variations in electrostatic capacitance occur. By electrically detecting the capacitance variations, the position of the finger 11, etc., can be detected.

[0033] The input sensor 2, as shown in FIGS. 4 and 5, is bonded on the rear surface of a planar housing 4 in front of a keyboard 5 in the PC 3, is fixed by using a double-sided bonding tape 6 or a bonding agent, and is not seen from the surface of the PC 3. The housing 4 is formed of an insulating material made of a molded resin. The thickness at the place where the input sensor 2 is bonded is less than or equal to approximately 2 mm, and more preferably, is less than or equal to 1 mm. Since the input sensor 2 is of an electrostatic capacitance type, when the proximity distance to the finger 11, etc., is greater than 2 mm, the sensitivity becomes poor, and therefore, the proximity distance must be less than 2 mm.

[0034] As shown in FIGS. 1 to 3, it is also possible to form a curved section 4A in a portion of the housing so as to bond the input sensor 2 on the rear surface of the curved section 4A. This is because the input sensor 2 can be bonded along the curved surface of the curved section 4A since the input sensor 2 is formed of a film, etc. Furthermore, if the input sensor 2 is bonded on the rear surface of the curved section 4A in this manner, by an operator tracing the surface of the curved section 4A when performing a pointing operation, the operation feeling is improved more than when tracing a planar surface.

[0035] Since the input device 1 is formed of the input sensor 2 in the form of a thin film and can be bonded on the rear surface of the housing 4, the input device 1 can be placed anywhere on the housing 4 of the PC 3, the flexibility of design is improved, and there are no limitations of design.

[0036] On the other hand, the details of the input sensor 2 are shown in FIGS. 6 to 9.

[0037] In FIGS. 6 to 9, the input sensor 2 has a flexible film substrate 10. This film substrate 10 is formed by an insulating synthetic resin sheet, such as PET (polyethylene terephthalate). In this film substrate 10, as shown in FIG. 6, an extension section 11 whose one side in its longitudinal direction protrudes toward the side is formed.

[0038] An X electrode layer 20X is provided on the underside of the film substrate 10. In the X electrode layer 20X, as shown in FIG. 5, an X-direction driving electrode 20Xd, in which a plurality (16) of X electrodes x1, x2, . . . , x15, x16 are formed in parallel at a predetermined spacing in the X direction, is formed. One end of each of the X electrodes x1, x2, . . . , x15, x16 is formed so as to extend up to the extension section 11.

[0039] In the X electrode layer 20X formed in the film substrate 10, a dummy electrode xd (a total of 15) is alternately formed between electrodes of the X electrodes x1, x2, . . . , x15, x16. As a result of providing the dummy electrodes xd in this manner, for example, an influence when water is stuck to the input sensor 2 can be scattered.

[0040] On the film substrate 10, a grounding electrode 21 extending up to the extension section 11 along the edge portion of the film substrate 10 is formed flush with the X-direction driving electrode 20Xd. Furthermore, in the space formed between the X-direction driving electrode 20Xd of the film substrate 10 and the grounding electrode 21 thereof, X switching electrodes 22, 23, and 24 formed of a plurality of electrodes are formed. The X-direction driving electrode 20Xd, the grounding electrode 21, the X switching electrodes 22, 23, and 24 are all formed by a screen printing method using a silver paste or a silver-based paste.

[0041] The surface of each of the electrodes 20X, 21, 22, 23, and 24 is provided with a flexible insulating film 12 which is formed by coating or printing an insulating resin (resist). This resist can be selected from, for example, a polyamide type, an epoxy resin type, a polyurethane type, and a polyester type, etc. At this time, in the insulating film 12, as shown in FIG. 8, a plurality of through holes h1, h2, . . . , h12, k2, k4, . . . , k10, m2, m4, . . . , m10, and s2 are formed. These through holes are formed at positions corresponding to one of the end portions of the X switching electrodes 22, 23, and 24. The electrodes shown in FIG. 7, in which the through holes corresponding to FIG. 8 are not formed, are electrodes for inspection purposes.

[0042] As shown in FIG. 9, a Y electrode layer 20Y is provided on the surface (under surface) of the insulating film 12. In the Y electrode layer 20Y, a Y-direction driving electrode 20Yd formed of a plurality (12) of Y electrodes y1, y2, . . . , y11, y12 is formed in a direction intersecting at right angles to the X-direction driving electrode 20Xd. One end of each of the electrodes y1, y3, y5, y7, y9, and y11 of some of the Y electrodes y1, y2, . . . , y11, y12 is formed so as to extend from both sides on the right and left (X direction) up to the position of a predetermined through hole shown in FIG. 8.